

### NIOS Nanomechanical Testers: Metal-ceramic and polymer

and polymer applications



#### **Optical microscopy**



Indenter positioning – displacement between microscope focus point and indenter tip is calibrated with 1 um accuracy

> Measuring linear size (and area) over the optical image







#### **Example: coated cutting tools**





Sample: cutting edge of the fraise

Sample: micro-drill for electronics industry applications



 $R_a = 70 \text{ nm}$  RMS = 86 nm  $R_z = 232 \text{ nm}$   $H = 30,8\pm6,5 \text{ GPa}$   $E = 675\pm105 \text{ GPa}$  $k = 2,15\pm0,05 \text{ kN/m}$ 

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Surface topography

<sup>713.51 nm</sup> Image of the residual imprint





#### **Example: multilayer coating on cutting tools**





Sample

Sample angle polish

Optical image of layered structure

Material	Hardness, GPa	Elastic modulus, GPa
Hard Alloy	19.0 ± 5.4	410 ± 140
TiCN	17.7 ± 4.5	340 ± 80
Al <sub>2</sub> O <sub>3</sub>	20.4 ± 4.0	340 ± 35
TiN	10.9 ± 3.3	360 ± 200



#### Localized nanomechanical tests





Topography: before indentation

Sample: aluminum alloy D16

Topography: after indentation





#### SPM aids indentation: pile-up analysis



### Pile-up analysis on steel 254 reference block HV 0.05





#### Study of delamination, adhesion and thickness

Sample: plasma sputtered diamond-like coating



	Thickness, nm	Load at which film is pulled, mN
1	460±20	6,2±0,3
2	265±10	5,9±0,3
3	960±70	11,0±2,6
4	1255±20	20,8±6

7



#### **Reciprocating wear tests**





#### Wear estimation of coatings



L=100 um — stroke length; v=0,13 Hz — reciprocating test frequency; t=7600 sec — testing time; h — indentor penetration depth; Indirect volume estimation over the optical micro-photograph of the groove



$$V = L \left( R^2 \arcsin\left[\frac{w}{2R}\right] - \frac{w}{2} \sqrt{R^2 - \frac{w^2}{4}} \right)$$

R=17 um — effective stylus radius; w — width of the residual groove; L=100 um — groove length;

Direct volume estimation over the SPM image



#### **ABI (automated ball indentation)**





![](_page_10_Picture_0.jpeg)

### 2D: H=f(x, y), static loading

Sample: gradient magnetic alloy of the following composition:

Chemical element	Cr	Ni	Si	Mn	С	V	Fe
Contents, %	16,5	7,5	0,48	1,0	0,08	0,04	remains

![](_page_10_Figure_4.jpeg)

Hardness map of the magnetic zone boundary

![](_page_10_Figure_6.jpeg)

Hardness profile across the magnetic zone boundary

#### Mapping 3D: H=f(x, y, z), hardness tomography

Sample: thin Ag film on glass substrate Optical micro-photo of the array of PUL indentations

![](_page_11_Picture_2.jpeg)

![](_page_11_Picture_3.jpeg)

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Volumetric quantitative map (tomogram) of hardness

![](_page_11_Figure_5.jpeg)

![](_page_12_Picture_0.jpeg)

#### Mapping 3D: hardness tomography

Sample: separation border between copper and Fe-Cr-Al alloy

![](_page_12_Picture_3.jpeg)

#### Sample: Polymer material for tooth prosthetics

Hardness (old\_s1)

0.32

0.30

0.28

0.26

0.24

0.22

0.20

0.18

H, (GPa)

![](_page_13_Picture_1.jpeg)

SECTION (Original) Y. (nm) 4X = 84.95 (um); dY = -254.52 (nm);  $\alpha$  = -0.2\* Y. (nm) 1250 1000 750 250 0 255 50 75 X. (um)

Surface topography and cross-section profile

Hardness vs. depth dependency for 3 polymer samples Elastic modulus (new\_s3\_ALL) E, (GPa) 5.4 5.2 5.0 4.8 4.6 4.4 4.2 4.0 3.8 3.6 Depth, (nm) 500 1000 2000 2500 Ò. 1500

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Elastic modulus vs. depth dependency for 3 polymer samples

It has been shown that chemical treatment reduces hardness and elastic modulus for 10-15%

Blue lines – before treatment Green lines – after treatment

# Depth, (nm) 1500 2000 2500

![](_page_14_Picture_0.jpeg)

#### Sample: Thin film of poly-n-isopropylacrylamide

![](_page_14_Picture_2.jpeg)

This polymer exhibits the properties of superabsorbent and is used in pharmaceutical industry during remedies extraction.

Thickness, nm	Hardness, GPa
100	0.5±0.1
5000	1.1±0.3

![](_page_14_Figure_5.jpeg)

Height profile of the pNIPAm film. Pile up effect depends on applied forces (F) and film thickness (*h*): a) F=5mN, *h*=5 $\mu$ m; b) F=1mN, *h*=100nm; c) F=2mN, *h*=100nm.

#### **Example: protective polymer coatings**

Samples: polymer materials with thermosetting siloxane protective coating

![](_page_15_Figure_3.jpeg)

Sample	Roughness , nm	Elastic (Young) modulus, GPa	Hardness, GPa	Elastic recovery rate, %
PC	11,8	2,2	0,27	72
PMMA	4,4	4,5	0,33	60
PC+coating	0,5	1,4	0,68	99

![](_page_15_Figure_5.jpeg)

Instrumented indentation loading-unloading curves

![](_page_15_Figure_7.jpeg)

Topography image after progressive scratch test (0 to 30 mN): PC (a) and PC+coating (b)

![](_page_16_Picture_0.jpeg)

#### Mapping 2D: H=f(x, y), dynamic loading

Sample: glass fibers in the polymer matrix

![](_page_16_Figure_3.jpeg)

accordingly, H or E if at least one of these quantities is known) as a function of depth or surface coordinates.

![](_page_17_Picture_0.jpeg)

#### Mapping 3D: hardness tomography

Sample: transition area between 2 polymer coatings on polydimethilsiloxane (PDMS) substrate

![](_page_17_Figure_3.jpeg)

Hardness tomography technique is based on combination of PUL or DMA method with precise indentor positioning over the regular XY grid on the sample surface

![](_page_17_Figure_5.jpeg)

## Samples: polyethylene multilayer film with thickness 50-300 um

Task: testing the mechanical strength and resistance to puncture of films on the substrates of polypropylene and steel

![](_page_18_Picture_3.jpeg)

Diamond flat punch indentor

![](_page_18_Figure_5.jpeg)

![](_page_18_Figure_6.jpeg)

Loading-unloading curves obtained with Berkovich diamond indentor

![](_page_19_Picture_0.jpeg)

### Thank you!